## Motor Protection Device ( $\mu \mathrm{eLEDX}-\mathrm{Ti}$ )



MODEL: $\mu \mathrm{eLEDx}-\mathrm{Ti}$ - Series

Apart from the motor protection, metering and monitoring functions, the device can accept four hardwired digital inputs (potential free contact signals) which can be used for Start, Stop,Emergency Stop and Local/ Remote (Auto/ Manual) control selection. These input commandscan also be transmitted to the remote-control room through RS485 communication network.

The device has three output relay potential free contacts, one relay with change-over contact (NO/NC) and two relays with NO contacts, which are pre-programmed for starter logics for DOLstarter, Star delta Starter, Soft Starter or can be configured by user for control logics in SCADA.

## Pre-programmed IoS

The inputs and outputs are pre-programmed for starter logics to control the Power contactors ofthe DOL or Star Delta starter or soft starter.
The pre-programmed starter logics can be selected by entering the required logic as numberedin the intelligent MPD or IO module settings for starter logics:

- 1-One output relay used for MPD, other IOs can be freely configured by user.
- 2-IOs programmed for Direct on line (DOL) Starter
- 3-IOs programmed for Star / Delta Starter
- 4- IOs programmed for Soft Starter
- 5-IOs can be freely configured by user as per their logic requirement


## PROTECTION:

- Over Load
- Single Phasing - CurrentBased
- Unbalance - CurrentBased
- Locked Rotor
- Under Current
- Short Circuit
- Earth Fault
- Over voltage \& undervoltage protection
- KW based under load


## GG SXGC

## FEATURES:

- LED Seven Segment Display, brighter pixilation
- Continuous scanning and display 3 phase currents and thermal capacity used, KW, PF and KWH
- Annunciation for each type of fault
- Numerical Algorithm for fast, reliable operation
- Thermal Overload curves selectable as per requirement, Excellent accuracy and longtime Stability of thermal curves due to complete software-based implementation
- Customized protection CT as per load requirement supplied with the relay
- Continuous self - supervision and fail-safe operation
- Annunciation in case, motor fails to stop afterprotection device issues trip command
- Man - Machine interface through keypad
- Up to five event trip records, FIFO based
- Reset Inhibit function, Hour Counter, Online calibration, Password facility (on demand)
- Robust mechanical design and adequate IP 54 degree of protection at the front of enclosure (when mounted on panel) which is shock proof non- metallic screw less unit


## OPTIONAL:

- RS 485 Data communication over MODBUS RTU protocol
- 4-20mA Analogue output
- Both RS 485 communication and 4-20mA AnalogueOutput
- Relay output for external alarm
- Password facility
- Fault history with Real time clock


## MEASURING \& DISPLAYPARAMETERS:

- R Phase Current (Ir)
- Y Phase Current (IY)
- B Phase Current (Ib)
- PF, KW \& KWH measurement
- True RMS current measurementwith 0.1A resolution
- Has Hour counter (Hr) (min)
- Has Start Counter
- Has Online Calibration facility


## RANGE:

- 0.2 to 12.5 Amp
- 0.8 to 25 Amp
- 2 to 62.5 Amp
- 4 to 125 Amp
- 40 to 250 Amp
- 80 to 500 Amp


## SPECIFICATIONS:

| Aux. supply | 230VAC (optional 110VAC / 415VAC), 50 Hz |
| :---: | :---: |
| CT | With External CT |
| *Rated current (As per motor FLC) | 0.2 to 500A (Seven CT ranges) |
| Rated Frequency | $50 \mathrm{~Hz} / 60 \mathrm{~Hz}$ |
| Mass of the device | 500gms. (approx.) |
| Mounting type | Flush mounted |
| Dimensions (L X W X D ) | $96 \times 96 \times 65 \mathrm{~mm}$ |
| Panel Cutout | $92 \times 92 \mathrm{~mm}$ |
| Thermal Overload setting range | 0.2 to 500A, as per CT range selected |
| Thermal Overload curve selection | 2.5C, 5C, 10C, 15C, 20C \& 30C (six curves) |
| Thermal Overload Operating time | As per thermal curve selected |
| Under current feature | Enable/Disable |
| Under current setting range | 10\% to 80\% FLC |
| Under current operating time | 1 to 60 sec |
| Locked Rotor setting range | Current range selected, pick up 3 X FLC |
| Locked Rotor pick up delay time (During starting) | 1 to 30 sec . |
| Earth fault trip start delay (during starting) | Enable or disable |
| (When enable; earth fault function will not operate during motor starting for 10seconds) |  |
| Earth fault setting range | 10\% to 30\% FLC |
| Earth fault operating time | 0.5 sec to 3 sec. |
| Short Circuit setting range | Current range selected, Pick up 8 X FLC |
| Short Circuit operating time | Instantaneous (about 1 Sec.) |
| Single phasing setting | Enable or disable |
| Single phase operating time | 2 sec (fixed) |
| Unbalance protection | Enable or disable |
| Unbalance protection setting range | 10\% to 40\% |
| Unbalance protection operating time | 3 to 10 sec . |
| Low voltage setting Range | 100 to 500V |
| Low voltage operating time | 1 to 60 sec |
| High voltage setting range | 100 to 500V |
| High voltage operating time | 1 sec (default) |
| Under load setting range | 0.115 to 144 KW |
| Under load operating time | 1 to 60 sec |
| Thermal Reset function | Enable or disable |
| Thermal Reset Inhibit time | 1 to 999 sec . (applicable when thermal reset is disable) |
| Data Output | RS 485 MODBUS - RTU Protocol, BaudRate - 9600, Word length - 8 |
| Analog Output | 4-20 Ma |
| Ambient service temperature | 0 deg. C to + 55 deg. C |
| Degree of protection (enclosure panel mounted) | IP 54 (Front side of the Device) |

[^0]Typical connection diagrams for $\mu$ eLEDx-Ti

DOL Starter


Star Delta Starter


Soft Starter


## CT DIMENSION



20 mm LINE CT
INNER DIA. -20 mm DUTER DIA. -47 mm

FOR 0.2 TO 6.25A, 0.4 TO 12.5A, 0.8 TO 25A, 2 TO 62.5A


35 mm LINE CT INNER DIA. -35 mm DUTER DIA.-59mm



55mm LINE CT INNER DIA.-55mm ZUTER DIA. -85 mm


[^0]:    *Note: Current range 80-500 Amp is available with all the above protection except short circuit protection.

